AVM 234S: 2500N Valve actuator with SUT positioner

How energy efficiency is improved

Automatic adaptation to valve, precision activation and high energy efficiency with minimal operating noise

Features

Technical data

- · Operation of 2-way or 3-way valves
- · For controllers with constant output (0...10 V or 4...20 mA) or switching output (2-point or 3-point control)
- · Stepping motor with Superior Universal Technology (SUT) electronic control unit and electronic, force-dependent cut-off
- · Simple assembly with valve; spindle is automatically connected after control voltage is applied (patented system)
- · Automatic detection of applied control signal (constant or switched); indicated by two LEDs
- · Coding switches for selecting characteristic and running time
- Type of characteristic (linear/quadratic/equal-percentage) can be set on the actuator
- · Automatic adaptation to the stroke of the valve (min. valve stroke 8 mm, max. valve stroke 49 mm). The measured stroke is saved and is not lost even in the event of a power failure
- · Direction of operation can be selected via screw terminals when making the electrical connection
- Crank handle for external manual adjustment with motor cut-off and as trigger for a re-initialisation
- Power supply 230 V with module or direct connection for 24 V~ / 24 V=; continuous activation also admissible with 230 V
- · Maintenance-free gear unit made of sintered steel; gearbox base-plate made of steel
- · Mounting column made of stainless steel; mounting bracket made of cast light alloy for fitting the valve
- · Electrical connections (max. 2.5 mm²) with screw terminals
- Three break-out cable inlets for M20 × 1.5 (2×) and M16 × 1.5
- Fitting vertically upright to horizontal. Suspended is not recommended as condensate, dripping water, etc. must be prevented from entering the actuator along the valve spindle.

Power supply		
	Power supply 24 V~	±20%, 5060 Hz
	Power supply 24 V=	±15%
	Power supply 230 V~	±15% (with accessories)
	Power consumption ¹⁾	24 V~/24 V= 10 W/20 VA
		230 V~ (with accessories) 13 W/28 VA
Deremeters		
Parameters	Pupping time	2/4/6 c/mm
		2500 N
	Actuating power	0 49 mm
	Response time for 3-point	200 ms
Positioner	Control signal 1	010 V, R _i >100 kΩ
	Control signal 2	420 mA, R _i = 50 Ω
	Positional feedback signal	010 V; load > 2.5 kΩ
	Starting point U ₀	0 or 10 V
	Control span ΔU	10 V
	Switching range X _{sh}	300 mV
Ambient conditions		
	Admissible ambient temperature	–1055 °C
	Admissible ambient humidity	< 95% rh, no condensation

Choose transformers for this value, otherwise malfunctions may occur











	Temperature of medium ²⁾	Max. 150 °C (or 240 °C with accessories)
Construction		
	Weight	4.1 kg
	Housing	Two-part, yellow
	Housing material	Fire-retardant plastic
Standards and directives		
	Type of protection	IP66 (EN 60529)
	Protection class	III (IEC 60730)
	EMC Directive 2004/108/EC ³⁾	EN 61000-6-2, EN 61000-6-4
	Low-voltage directive 2006/95/EC	EN 60730-1, EN 60730-2-14
	Over-voltage categories	III
	Degree of contamination	III

Description
Auxillary contacts Infinitely variable, min. 100 mA and 12 V permissible load 6(2) A
Potentiometer, 1000 Ω, 1 W; 24 V
4-20 mA position feedback signal, for 24VAC/DC, output load resistor max 600 ohm
Hi temperature adaptor (required when temperature of the medium is 150 °C240°C
odules can be added for 2-point/3-point and continuous activation; additional power 2 VA
Description
230 V ±15%, supply voltage
100 V ±15%, supply voltage
Adjustable connection for Clorius valves DN15-150 for AVM234 and AVF234 actuators
Cable screw fitting M16 × 1,5
Cable screw fitting M20 × 1.5
Split-range unit for adjusting sequences between 0 and 10 V, fitted in separate junction box

³⁾ EN 61000-6-2: (HF immunity, limitation of feedback signal between 80 MHz and 1000 MHz criterion B, other-wise criterion A)



 $_{2)}$ $\,$ For higher temperatures of the medium (<240 °C), use an adaptor (see accessories) $\,$

Description of operation

Depending on the type of connection (see connection diagram), the actuator can be used as a continuous (0...10 V and/or 4...20 mA), 2-point (OPEN/CLOSE) or 3-point actuator (OPEN/STOP/CLOSE). The running time of the actuator can be set with switches S1 and S2 according to the relevant requirements. Switches S3 and S4 are used to configure the characteristic (equal-percentage, linear or quadratic).

The external crank handle enables manual positional setting. When the crank handle is folded out, the motor is switched off. After the crank handle is folded back, the target position is approached again (without initialisation). When the crank handle is folded out, the actuator remains in this posi-tion.

Intended use

This product is only suitable for the purpose intended by the manufacturer, as described in the "Description of operation" section.

All related product regulations must also be adhered to. Changing or converting the product is not admissible.

Engineering and fitting notes

Suspended is not recommended as condensate, dripping water, etc. must be prevented from entering the actuator along the valve spindle.

The valve is mounted directly on the actuator and fixed with screws (no further adjustments are required). The actuator is connected with the valve spindle automatically. As delivered ex works, the actuator spindle is in the middle position. The housing contains three break-out cable inlets which are broken out automatically when the cable inlet is screwed in. The concept of stepping motor/electronics enables parallel operation of multiple valve actuators of the same type. The cross-section of the power cable must be selected based on the cable length and the number of actuators. With five actuators wired in parallel and a cable length of 50 m, we recommend a cable cross-section of 1.5 mm² (power consumption of the actuator × 5).

The maximum equipment for the actuator is one 230 V module, one additional accessory component (auxiliary contact or potentiometer) and the split-range unit.

Outdoor installation

If installed outside of buildings, the devices must be additionally protected from the weather.

Initialisation and feedback signal

The actuator initialises itself autonomously when it is connected as a continuous actuator. Once a voltage is applied to the actuator for the first time, the actuator moves to the lower limit stop of the valve and thus enables automatic connection with the valve spindle. Then it moves to the upper stop and the value is detected and saved via a travel measurement system. The control signal and the feedback are adjusted to this effective stroke. In case of a power failure or the removal of the power supply, no re-initialisation is carried out. The values remain saved.

For a re-initialisation, the actuator must be connected to the power supply and there must be a constant input signal at 3u or 3i. An initialisation is triggered by folding the crank handle out and back twice within 4 s. Then the two LEDs flash red.

During initialisation, the feedback signal is inactive or equal to the value "0". Initialisation is carried out with the shortest running time. The re-initialisation is only valid when the whole process is complete. Folding the crank handle out again interrupts this process.

If the actuator detects jamming, it reports this by setting the feedback signal to 0 V after approx. 90 s. During this time, the actuator tries to overcome the jamming. If the jamming can be overcome, the normal control function is activated again, and the feedback signal is restored.

With 2-point or 3-point control, no initialisation is performed. The feedback signal is inactive.



Connection as 2-point valve actuator (24 V)

This activation (OPEN/CLOSE) can be performed via two wires. The voltage is applied to terminals 1 and 2a. When voltage (24 V) is applied to terminal 2b, the actuator spindle moves out. After this voltage is switched off, the actuator moves to the opposite end position. In the end positions (valve limit stop or maximum stroke reached) or in the case of an overload, the electronic motor cut-off is activated (no limit switches).

The running times can be set using the coding switch. The characteristic cannot be selected here (the result is the characteristic of the valve). Terminals 3i, 3u and 44 must not be connected.

Connection as 3-point valve actuator (24 V)

If voltage is applied to terminal 2a (or 2b), the valve can be moved to any desired position. If voltage is applied to terminals 1 and 2b, the actuator spindle moves out. It moves in when the electrical circuit is closed via terminals 1 and 2a.

In the end positions (valve limit stop or maximum stroke reached) or in the case of an overload, the electronic motor cut-off is activated (no limit switches). The direction of the stroke can be changed by swapping the connections.

The running times are set using the coding switch. The characteristic cannot be selected here (the result is the characteristic of the valve). Terminals 3i, 3u and 44 must not be connected.

Connection with 230 V or 100...110 V as 2-point/3-point or with continuous activation of valve actuator (accessory)

The built-in positioner controls the actuator depending on controller's output signal y.

A voltage signal (0...10 V–) at terminal 3u or a current signal at terminal 3i serves as the control signal. If there is a control signal at the two terminals (3u (0...10 V) and 3i (4...20 mA)) at the same time, the input with the higher value has priority.

Direction of operation 1 (mains power supply on internal connection 2a):

When the positioning signal is increasing, the actuator spindle moves out.

Direction of operation 2 (mains power supply on internal connection 2b):

When the positioning signal is increasing, the actuator spindle moves in.

The starting point and control span are fixed. To set partial ranges, a split-range unit is available as an accessory (only for voltage input 3u) – see the split-range unit function – which is intended to be installed in the actuator.

After the connection of the power supply and the initialisation, the actuator moves to every valve stroke between 0% and 100%, depending on the control signal. Thanks to the electronics and the travel measurement system, no stroke is lost, and the actuator does not require periodic re-initialisation. When the end positions are reached, this position is checked, corrected if necessary, and saved again. It is thus possible to operate multiple actuators of the SUT type in parallel. The feedback signal $y_0 = 0...10$ V corresponds to the effective stroke of 0 to 100%.

If the control signal 0...10 V or 4...20 mA is interrupted with direction of operation 1, the actuator spindle moves in completely, or moves out completely with direction of operation 2.

The coding switch can be used to set the characteristic of the valve. An equal-percentage or quadratic characteristic can only be generated when the actuator is used as a continuous actuator. Additional switches can be used to select the running times (with the 2-point, 3-point or continuous functions). Continuous actuation can also be used with a power supply of 230 V or 110 V (accessory required). You must ensure that the neutral wire of the controller is connected to the control voltage. The neutral wire of the power supply may only be used for the module.

LED indicator: The indicator consists of bi-colour LEDs (red / green).

Both LEDs flash red	Initialisation
Top LED lights up red	Top limit stop or "CLOSED" position reached
Bottom LED lights up red	Bottom limit stop or "OPEN" position reached
Top LED flashes green	Actuator is running, moving to "CLOSED" position
Top LED lights up green	Actuator is stopped, last direction of travel "CLOSED"
Bottom LED flashes green	Actuator is running, moving to "OPEN" position
Bottom LED lights up green	Actuator is stopped, last direction of travel "OPEN"
No LED lights up	No power supply (terminal 2a or 2b)
Both LEDs flash red and green	Actuator is in manual mode

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Split-range unit (accessory)

This accessory can be built into the actuator or externally housed in an electrical junction box. Starting point U0 and control span ΔU can be set with the potentiometer. In this way, several control units can be operated by the control signal of the controller in sequence or in a cascade. The input signal (partial range) is converted into an output signal of 0...10 V.

Additional technical information

The yellow housing, consisting of the front part, rear part and connecting lid, only serves as a cover. The DC motor, electronic control unit, load-bearing section and maintenance-free gear unit are located in the housing. The actuator spindle and the column are made of rust-proof material. The inner printed circuit boards and the gear unit are made of steel. The valve spindle guide and the valve neck coupling are made of die-cast aluminium.

Note on ambient temperatures: With a media temperature of up to 110°C in the valve, the ambient temperature is allowed to reach 60°C. With a media temperature above 110°C, the ambient temperature must not exceed 55°C. Otherwise, the intermediate piece accessory 1-0152285 must be fitted.

Auxiliary change-over contacts

Switch rating max. 250 V~, current min. 250 mA at 12 V (or 20 mA at 20 V) Switch rating max. 12...30 V=, current max. 100 mA

Warning

- If there is a high media temperature in the valve, the actuator columns and the spindle can attain similarly high temperatures.
- If damage can occur due to the failure of the control unit, additional protective measures must be implemented.



Desired character. curve	Switch coding	Characteristic curve for valve	Characteristic curve for drive	Effective on valve
Equal percentage	1 2 3 4 On 000 Off 000	v Stroke	Signal	v = % Signal
Quadratic	1 2 3 4 On Off	v Stroke	Signal	V X ² Signal
Linear	1 2 3 4 On Off	v Stroke	Signal	V lin Signal
Equal percentage	1 2 3 4 On Off	v Stroke	Stroke	v = %
Linear	1 2 3 4 On Off	v Stroke	Stroke	v lin Signal
	factory setting			

Run time per mm	Switch coding	Run time for 14 mm stroke	Run time for 20 mm stroke	Run time for 40 mm stroke
2s	1 2 3 4 On Off	28s ± 1	40s ± 1	80s ± 4
4s	1 2 3 4 On Off	56s ± 2	80s ± 4	160s ± 4
6s	1 2 3 4 On 000 Off	84s ± 4	120s ± 4	240s ± 8
	On Off			
factory setting				

Disposal

When disposing of the product, observe the currently applicable local laws. More information on materials can be found in the Declaration on materials and the environment for this product.

Clorius CONTROLS

Connection diagram







Accessories











Temp. adaptor





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