

99.66.05-A GB

Electro-Pneumatic Positioner EPR Series Instruction Manual







1. Read all safety instructions in this manual carefully before using this EPR positioner. All work should be done by staff with the necessary training and experience. 2. The air filter regulator should be installed before this EPR positioner.

- 3. The EPR positioned approved for ATEX Eex md IIB T5 must be connected to a fuse with The EPK positioned approved for ATEX Lex that its To must be connected to a fact the following ratings:
 Max 125mA, breaking capacity 35A
 Suitable 1/2" PF threaded, certified EEx d cable glands and plugs must be used.

Port Number Suct

1. Part Number System					
EPR — Prote	ection ass Feedback Shaft Pressure Gauge (SUP. OUT) Out	re Position Conn ce Feedback Thre	ection Dome High Mounting adds Indicator Temp Bracket		
Description	Code	Description	Code		
Protection Class:	F: Flameproof Ex md IIB T6 D: Flameproof Ex md IIC T6 A: Flameproof Eex md IIB T5 ATEX	Connection Threads: (pneumatic – electrical)	3: PT 1/4 – PT 1/2 (standard) 4: NPT 1/4 – NPT 1/2 5: PT 1/4 – M20 x 1.5		
	I: Intrinsic safety (Ex la IIB 16) W: Weatherproof to IP66	Dome Indicator:	N: Flat indicator (standard) D: Dome indicator		
Feedback Shaft:	N: NAMUR shaft (direct mounting) A: Fork lever M6x40L B: Fork lever other size on request	High Temperature: (only for weatherproof	T: 70 ℃ (standard) H: 120 ℃ (without position feedback option)		
Pressure Gauge:	1: 6 bar (90 psi) 2: 10 bar (150 psi)	type)	$85^\circ\!\!\!\!^\circ ^\circ\!\!\!\!^\circ$ (with position feedback option)		
Pilot Valve Orifice:	S: Standard (actuator volume over 180 cm) M: Small orifice (Φ1.0 or Φ0.7) (actuator volume 90~180 cm)	Mounting Bracket:	N: None R: Multi-size NAMUR bracket for DIN VDI/VDE 3845 F: DHCT bracket 80x30 for fork lever type E: Multi-size NAMUR bracket		
Position Feedback: (only for weatherproof type)	N: None (standard) O: Position transmitter (4~20mA output signal) L: 2 x SPDT limit switch M: O+L		for fork lever type		

2. Specifications

		EPR	
	Rotary Type (Cam Feedback)		
	Single	Double	
Input Signal	4 ~ 20mA DC (Note. 1)		
Input Resistance	235 ± 15Ω		
Air Supply	Max. 7.0bar (100psi)	free of oil, water, and moisture	
Standard Stroke	60 ~ 1	100 ° (Note. 2)	
Pneumatic Connections	PT 1	/4 or NPT 1/4	
Electrical Connections	PT 1	/2 or NPT 1/2	
	Ex md IIB T6, Ex md IIC(H2) T6, I <u>P6</u> 6, Ex ia IIB T6		
Protection Class	Eex md IIB T5 ATEX		
Ambient Temperature	-20 ~ +	70℃ (standard)	
Pressure Gauge	Sta	inless Steel	

Output Characteristics	Lin	ear
Linearity	Within ± 1.0 % F.S	Within ± 1.5 % F.S
Sensitivity	Within ± (0.5 % F.S
Hysteresis	Within ± '	1.0 % F.S
Repeatability	Within ± (0.5 % F.S
Air Consumption	5 LPM (Sup	o. 1.4kgf/cm²)
Flow Capacity	80 LPM (Su	p. 1.4kgf/c㎡)
Material	Aluminum	n Die-cast
Weight	2.9 kg (with t	terminal box)

Note: 1) It is adjustable to set 1/2 spilt range for 4-12ma input signal or 12-20mA input signal. 2) Stroke can be adjusted to 0~60° or 0~100°

3. Mounting and Selecting RA (reverse acting) or DA (direct acting)

CAUTION: To reduce the risk of ignition of hazardous atmospheres, disconnect the device from the supply circuit before opening. Keep assembly tightly closed during operation.

A. Mounting with NAMUR type

The EPR positioner has the NAMUR shaft as standard which can be directly mounted to the top pinion (VDI/VDE 3845) of the pneumatic rotary actuator.

- ① Mount the NAMUR multi-size bracket to the pneumatic rotary actuator with the enclosed bolts (4 x M5) as shown to the right.
- 2 Mount the EPR positioner to the bracket and insert the EPR positioner feedback shaft into the actuator top pinion (output shaft) as shown to the right.

③ Fix the EPR positioner to the bracket with the enclosed bolts (4 x M6).



NAMUR Mounting

A multi-size bracket is assembled for 80x30x20 as a standard factory setting. But the user can re-assemble it for 80x30x30, 130x30x20, and 130x30x30 according to requirements as shown below.



Multi-size bracket (NAMUR mounting)

B. Mounting with fork lever type

Mount the EPR positioner to the actuator with DHCT bracket (80x30) as shown to the right. Be sure that the feedback lever shaft "A" is placed in the orifice for the fork lever "B" and they are in alignment with a rotary actuator output shaft.

C. Cam and Indicator Adjustment



WARNING: When adjusting or replacing cams, be sure to shut off air supply to the EPR positioner. Otherwise, the EPR positioner might react suddenly and cause damage or injury.

RA (reverse acting) is a standard factory setting.

① Loosen a flange nut on a cam and reverse a cam for DA setting. Match the part of the cam with "0" marked on it with the center of bearing as shown below. The span adjusting arm unit should now be aligned.



- ② Tighten the flange nut of the cam after setting the cam.
 ③ After cam installation, proceed to adjust zero and span. Once this is complete, secure the indicator with the bolt (M6) to the feedback shaft according to the actuator type (RA or DA) as shown below. The position for the indicator should be arranged in the scale (0-90 degrees) shown on the cover.



4. Air Connections



5. Internal View

Never move the seat adjuster. It was already set at the factory precisely.





6. Span and Zero Adjustment

- ① Check the proper installation of the EPR positioner and the feedback shaft.
- 2 Check the proper position of a cam according to the actuator type (direct acting or reverse acting).
- ③ Connect all air connections.
- ④ Supply air and set the input signal to 4mA. Turn the zero adjusting screw clockwise or counter clockwise to set the zero position.
- (5) Check the stroke of the control valve by setting the input signal to 20mA. If the stroke does not meet 100%, turn the span adjusting screw clockwise or counter clockwise until 100% is reached.
- 6 Set the input signal back to 4mA and adjust the zero adjusting screw until the zero point is reached.
- 8 If the strokes of the control valve perfectly meet 0% and 100%, each setting point of 8, 12, and 16mA is automatically reached.

NOTE: Due to variations in circuitry and environmental effects, often 0% is set at 4.5mA and 100% at 19.5mA to make sure that at the end points the valve will be fully open or fully closed.

7. Wire Diagrams

A. Standard and With Position Transmitter or Limit Switches



CAUTION: Always check that the electrical load is within the range stated on the nameplate. Failure to remain within electrical ratings may result in damage to or premature failure of the electrical switches, sensors or transmitter electronics.

B. With Position Transmitter and Limit Switches



8. Position Transmitter (4...20mA output signal)



B. Specifications

Power Supply Rating	5.5 ~ 30V DC loop-powered
Recommended Power Supply	24V DC
Output Signal	4~20mA
Operating Temperature	-20° to 70 ℃
Load Impedance	0~600 ohms
Max. Output	30mA DC
Linearity	± 1.0 %
Hysteresis	1.0 % of full scale
Repeatability	± 0.5 % of full scale
Adjustment	Zero and Span in terminal box



E. Span and Zero Adjustment

① Select RA or DA on a board in the terminal box. For reference, RA (reverse acting) is a standard factory setting.

② Supply 4mA input signal and turn the zero adjusting screw on a board clockwise or counter clockwise until output signal becomes 4mA.

③ Supply 20mA input signal and turn the span adjusting screw on a board clockwise or counter clockwise until output signal becomes 20mA.

④ Repeat the process of ② to ③ until output signal approaches input signal.

1. Be sure that Span and Zero of the EPR positioner should be exactly set before setting Span and Zero of the position transmitter.

- 2. Be sure that 5.5 30V DC should be supplied in case of using the mA tester (multimeter tester).
- 3. Check a loop power if the output power indicating lamp (6) is not on.

9. Limit Switches (open and close)

Contacts	SPDT Form C
AC Rating	16A 1/2HP 125/250VAC
DC Rating	0.6A 125VDC / 0.3A 250VDC
Adjustment	Cams with set screws (L-wrench included for setting)

10. Optional Restricted Pilot Valve Orifice



For improved control using smaller actuators, a restricted pilot valve orifice kit is included with the EPR positioner. To install, the pilot valve must be removed from the EPR positioner. Remove four screws holding the pilot valve to the EPR positioner body. As you remove the pilot valve, be sure to hold the compensation spring in place. Flip the valve so the bottom faces you. Remove the o-rings from



the *out 1* and *out 2* ports (as shown in the diagram at right). Place the orifice plates in their place with new O-rings above them, and re-install the pilot valve, making sure the compensation spring is back in place. The EPR positioner is now set up for smaller actuators.

11. Troubleshooting Tips



12. Dimensions





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